| Wayne | INSTALLATION INSTRUCTIONS | ADV-X MODEL 885 |
| :---: | :---: | :--- |
| Way | Wayne |  |
| Doanton | EXTREME EXTERIOR HIGH SPEED RUBBER DOOR | Dalton |



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## A WARNING

Advanced Performance service doors are large, heavy objects that move with the help of electric motors. Since moving objects and electric motors can cause injuries, your safety and the safety of others depends on you reading the information in this manual. If you have any questions or do NOT understand the information presented, call your nearest service representative.

In this section and those that follow, the words "DANGER", "WARNING", and "CAUTION" are used to stress important safety information. The word:

ADANGER indicates an imminently hazardous situation which, if not avoided, will result in death or serious injury.
AWARNING indicates a potentially hazardous situation which, if not avoided, could result in death or serious injury.
ACAUTION indicates a potentially hazardous situation which, if not avoided, may result in injury or property damage.
The word NOTE is used to indicate important steps to be followed or important considerations.

1. Read manual and warnings carefully.
2. Keep the door in good working condition.
3. This door is equipped with a sensing edge, check sensing edge operations daily. Make any necessary repairs to keep it functional.
4. All models are equipped with an overcurrent device. This must be manually reset following an overcurrent condition.
5. Keep instructions in a prominent location near the Control Panel.

$\left.$| POTENTIAL <br> HAZARD | EFFECT | PREVENTION |
| :---: | :---: | :--- |
| MOVING DOOR |  |  |$\quad$| A WARNING <br> Can Cause Serious <br> Injury or Death |
| :---: | | Do NOT operate unless the doorway is in sight and free of obstructions. Keep people clear of |
| :--- |
| opening while door is moving. |
| Do NOT change control to momentary contact unless an external reversing means is |
| installed. |
| Do NOT operate a door that jambs. | \right\rvert\,

## SAFETY INSTRUCTIONS

## Electrical Power Requirements for all ADV-X Door Models

All ADV-X models 881, 882, and 883 are available in single phae and 3 -phase voltages. Single phase voltages are available in 115VAC and 240 VAC. 3 phase voltages are available in $240 \mathrm{VAC}, 480 \mathrm{VAC}$, and 575 VAC . ADV-X model 884 and 885 are available in 3 phase voltages only. YOUR LOCAL CODES MAY REQUIRE THAT THE INCOMING POWER TO YOUR DOOR HAVE A LOCK-OUT / TAG-OUT EQUIPPED FUSED DISCONNECT SWITCH (TO BE FURNISHED BY OTHERS) WITHIN EYESIGHT OF THE DOOR'S CONTROL PANEL. Incoming power wiring must meet all NEC and local building codes, plus be properly sized for the control panel's amperage rating on the nameplate. To reduce the risk of electric shock, the chassis of the control panel must be properly grounded.

[^0]
## SECTION 2-GENERAL INFORMATION

## COMPONENT IDENTIFICATION DRAWING

Extreme exterior high speed rubber door with parts.


Please note that components and component locations are shown here for REFERENCE ONLY. Your unit installation and component locations may be different.

## SECTION 2 - GENERAL INFORMATION (continued.....)

## DOOR INSTALLATION DATA SHEET

A sample of the "DOOR INSTALLATION DATA" sheet is shown here. Locate the work order "Door Installation Data" sheet inside the door hardware box. You will need to refer to the "Door Installation Data" sheet. See Figure 2.
Factory order number on door components must match with factory order number on the "Door Installation Data" sheet. Each door has it's own individual sheet.

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F벼N №HTM
H네N MOTTH:


BADIO MONTNOL
MOTIOA ETTRLTOR
HOTTM EST PTHOTIT








## Dach 1whtallatios EnTH



Fig 2

SECTION 2-GENERAL INFORMATION (continued.....)

## PRE-INSTALLATION CHECK LIST

Verify that the door installation can be accomplished before proceeding:

- Locate the work order "DOOR INSTALLATION DATA" sheet, see Figure 2, inside the door hardware box.
- Does the wall opening shown in FIG 3 match the Opening Width and Height shown on the "Door Installation Data" sheet?
- Can the guides be installed plumb?
- Check the sill for level. If sill is not level, mark the high sill location on the low side jamb.
- Guides are designed to rest on sill.
- Does the "G" dimension on your "DOOR INSTALLATION DATA" sheet match your opening width. See FIG 4



Fig 4

## SECTION 3 - DOOR INSTALLATION

## ! WARNING

Follow instructions and use proper lifting equipment and correct lifting procedure to avoid serious injury or death.

## STEP 1 INSTALL GUIDES

- Check "G" Dimension as illustrated in Fig 4 on page 5. "G" Dimension must match your "DOOR INSTALLATION DATA" sheet.
- Ideally your "G" dimension will exactly match your opening width. If it does not you must mount your guides so the "G" dimension is held over the entire height.
- Locate the guide assemblies and lay them on the ground in front of the opening.
- Remove pre-installed hardware holding the guide assemblies together and disassemble the guide assemblies. See FIG 5.
- Use clamps to mount the wall guides to the wall as shown in FIG 6.
- Check "G" Dimension as illustrated in Fig 4 on page 5. "G" Dimension must match your "DOOR INSTALLATION DATA" sheet
- Both guides MUST be on a level line and both guides MUST be plumb.
- The " $G$ " Dimension must be held within $1 / 8$ " over the entire height of the guides.
- Install the wall anchors mounting the wall guides to the wall as shown in FIG 7.
- Recheck G dimension to be sure it is correct.
- Remove clamps.



## SECTION 3 - DOOR INSTALLLATION (continued.....)

A WARNING
Rapidly closing curtain could result in death or serious injury. Do not remove factory banding around curtain assembly until step 5.

## : WARNING



- Attach the lintel assembly to the lintel as shown in FIG 10. Lintel seal should be flush with the bottom of the lintel.

- Remove the pre-installed bolts, washers, and nuts from the idler bearings. See FIG 11
- Slide the idler bearings onto the shafts at the ends of the idler barrel assembly. Do not tighten the set screws yet. Also loosen the set screws in the set colors. See FIG 12
- Insert one end of the idler barrel shaft into the hole in the stage bracket as shown in FIG 13.
- Insert the other end of the idler barrel shaft into the hole on the opposite stage bracket.
- Center the barrel between the two stage brackets.
- Reinstall the idler bearings using the hardware you removed earlier in this step. See FIG 14
- Recheck that the barrel is centered between the two stage plates and tighten the set screws in the bearings on both sides. Then slide the set colors against the bearings and tighten the set screws in them.


Follow instructions and use proper lifting equipment and correct lifting procedure to avoid serious injury or death.

- Remove six sets of pre-installed bolts, washers, and nuts from the top surface of the stage bracket.
- Lift the header assembly using a fork lift or other appropriate lifting equipment and lower it onto the stage brackets as shown in FIG 15 and 16.
- Be sure the stage pins slide into the holes in the headplate. See FIG 16. These pins will align and center the header assembly.
- Reinstall the bolts, washers, and nuts to secure the header assembly onto the guides.


## STEP 5 INSTALL MOTOR

- Remove pre-installed motor mounting hardware from the mounting bracket as shown in FIG 17. Loosen the mounting bracket hardware so the bracket can slide back and forth as needed. See FIG 17.
- Slide motor onto shaft as shown in FIG 17.

- Re-install the motor mounting hardware, securing the motor.
- Re-tighten the mounting bracket hardware.
- Rotate the curtain assembly shaft to align it with the keyway on the motor.
- Insert the key into the keyway.
- Install the sprocket by sliding it onto the shaft and attach the chain to this sprocket and the encoder sprocket as shown in FIG 18.
- Be sure the two sprockets are aligned with each other. Then tighten the set screws in the sprocket. - The encoder bracket attachment bolts, holding the encoder assembly onto the motor, may need to be adjusted to achieve proper chain tension. See FIG 18


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## SECTION 3 - DOOR INSTALLATION (continued.....)

STEP 6 RELEASE THE CURTAIN ASSEMBLY

- Check to be sure the pre-installed bearings and set collars in the header assembly have not loosened during shipping.
- Remove factory banding around curtain.
- You will need one or more assistant(s) to help lower the curtain for the first time.
- Pull the red handled cord on the motor to activate the chain hoist.
- The assistant(s) will need to push the bottom bar and curtain assembly in towards the wall while it is being lowered with the hand chain, so it will be routed correctly behind the idler barrel as shown in FIG 21.
- Be sure the curtain assembly passes behind the idler barrel and into the bell mouth and guides as shown in FIG 21.
- When the curtain is fully lowered pull the green handled cord to deactivate the chain hoist.

STEP 7 INSTALL JUNCTION BOX
Find a suitable and easily accessible location for the Junction Box. See Fig. 20

- Locate the Junction Box on the wall near the motor, but OUTSIDE the motor cover. Verify component cables will reach before mounting the Junction Box.
- Away from heat sources.
- With no interference of moving parts of the door system.
-Where cables can be well secured while preventing unnecessary strain.
- Use the Junction Box exterior mounting fixtures to mount to the wall using appropriate fasteners. (Fasteners not provided)


STEP 8 INSTALL CONTROLLER
Find a suitable and easily accessible location for the Controller. See FIG 20.

- Adjacent to the door, on the wall, about 5 feet above the floor at the center of the panel (roughly eye level).

It may be mounted higher in commercial applications to reduce tampering.
-Where all moving parts of the door system are visible while at the control panel.

- Away from heat sources.
- With no interference of moving parts of the door system.
- Where cables can be well secured while preventing unnecessary strain.
- Mount the Control Panel to the wall using appropriate fasteners. (Fasteners not provided) Use supplied mounting tabs as necessary.


## SECTION 3 - DOOR INSTALLLATION (continued.....)

STEP 9 MOTOR AND CONTROLLER WIRING

- For instructions on wiring the controller see section 4 and 5 pages 14-23.


## STEP 10 INSTALL HOOD AND MOTOR HOUSING

- Install the hood and motor c using the self drilling screws provided.


## STEP 11 APPLY WARNING LABEL

Product safety label must be installed.

- Place safety label on drive side guide at a readable height.
- Place sensing edge safety label on the bottom bar.

NOTE: Product safety labels should be periodically inspected and cleaned by the product user as necessary to maintain good legibility. Order replacement safety labels from the door manufacturer as required to maintain legibility.


## SECTION 4 - LOW VOLTAGE WIRING

STEP 1 CONNECT CONTROLLER LOWVOLTAGE WIRING (EXTERNAL)
Connections to the door are completed by attaching the two screw-in cables to the control panel's base, Fig 18 page 16.
-5 pin cable connector (See Fig 20 and 21 on page 18)

- Position Sensor
-12 pin cable connector (See Fig 18 on page 16)
- Photoeye Receiver
- Photoeye Transmitter
- Sensing Edge
- Hand Crank Interlock Switch
- Optional Input 1


## STEP 2 INSTALL OPTIONAL DEVICES

## INSTALL MOTION SENSOR (optionally purchased)

Motion Sensor is an optional component purchased separately and does not come with door.

- Follow the installation instructions accompanying the Motion Sensor.
- Install wiring per wiring diagram FIG 23 page 19.


## INSTALL LOOP DETECTOR (optionally purchased)

Loop Detector is an optional component purchased separately and does not come with door.

- Follow the installation instructions accompanying the Loop Detector.
- Install wiring per wiring diagram FIG 24 page 19.


## INSTALL RADIO CONTROLS (optionally purchased)

Radio Controls are an optional component purchased separately and does not come with door.

- Follow the installation instructions accompanying the Radio Controls.
- Install wiring per wiring diagram FIG 22 page 19.


## INSTALL WALL MOUNTED PUSH BUTTON (optionally purchased)

Wall Mounted Push Buttons are an optional component purchased separately and does not come with door. - Install wiring per wiring diagram FIG 8-B page 36.

## STEP 3 CONNECT OPTIONAL DEVICES

Two options may be connected to the Junction Box by the installer. Additional options must be wired to the spare inputs on the Control panel. Use the corresponding option inputs.

- Radio Remote to the Junction Box connector 6 labeled "Option 2".
- Floor loop to the Junction Box connector 5 labeled "Option 1".
- Motion Detector to the Junction Box connector 5 labeled "Option 1".
- Wall mounted push button stations to the main Control Panel Fig. 8-J on page 51.

Note: When installing push buttons, use the 24 V supplied by the Control Unit as the common.

SECTION 4 -LOW VOLTAGE WIRING (continued.....)

1. MAIN COMPONENT OVERVIEW, FIG 16 AND 17


TO JUNCTION BOX

1. SENSING EDGE (WHITE)
2. INTERLOCK (GREEN)
3. NOT USED
4. PHOTOEYE RECEIVER (GRAY)
5. OPTION 1 (PINK)
6. OPTION 2 (RED)
7. NOT USED
8. NOT USED
9. NOT USED
10. COMMON (OV) (BLUE)
11. POWER (24V) (BROWN)
12. GND (GREEN/YELLOW)


TO POSITION SENSOR

1. 12 V (BROWN)
2. A SIGNAL (WHITE)
3. B SIGNAL (BLUE)
4. OV (BLACK)
5. PULSE (GRAY)


Fig 18 Cables to Control Panel



Fig 19 JUNCTION BOX WIRING
Connections for most factory wired external control functions.

## SECTION 4 -LOW VOLTAGE WIRING (continued.....)

## 4. POSITION SENSOR WIRING CONNECTIONS AND SETTINGS

The Position Sensor comes pre installed to the motor. See Fig 20 for location.

- Attach one end of the M12 position sensor cable to the Position Sensor.
- Attach the other end of the M12 position sensor cable to the Control Panel.


Fig 21 POSITION SENSOR CABLE

## SECTION 4 - LOW VOLTAGE WIRING (continued.....)



## 5. Options wiring and settings

-Wire the supplied cables from the junction box to the optional equipment as shown in FIG 23, and FIG 24.
-Wire the Radio receiver directly into the controller (through an available opening) as shown in FIG 22.

## A CAUTION

Door will open/close once connected.
A. For the radio receiver, wire the supplied receiver load into the control unit from MAN1 to 24VDC (blue terminal).

1. Access the menu and navigate to system config-> Inputs-> MAN1-> Logic.
2. Select NC parameter and exit the menu.
3. To update the auto close timer, access the express menu->MAN1 Timer

FIG 24

-
B. The motion detector and loop detector can be operational once connected to the junction box. They are wired for the default configuration.

1. To update the auto close timer, access the express menu->AUTO1 Timer.

## WARNING

Before beginning this phase of the installation, ensure power supply is DISCONNECTED to avoid serious injury or death!

## A CAUTION

ADV-X Door Models must be supplied by a grounded Wye voltage supply, e.g. $208 \mathrm{Y} / 120,480 \mathrm{Y} / 277$. Ungrounded voltage supply sources must be avoided, e.g. 480 VAC , 240 VAC or 120 VAC Delta systems should NOT be used. Voltage unbalance is a common occurrence on Delta supply systems, which power both single phase and three phase loads, which can lead to unequal voltages on each phase leg. Voltage unbalance can cause deterioration of motor performance, such as loss of torque, overheating, decrease the winding insulation life, and can cause motor starter contacts, located in the control panel, to permanently "weld" closed. Voltage unbalance can be caused by inadequate conductor sizing, Delta transformer sizing, excessive single-phase loads, poor grounding, or intermittent high resistance faults (Faults which do NOT generate high - enough fault currents to trip an Over Current Protection device, but will cause the distributed capacitance in an ungrounded three phase system to shift. This shift may cause destructive over-voltages to occur).
Overhead Door Corporation's warranty WILL NOT cover damage caused by failure of the motor, control panel or other electrical components due to the use of an inadequately grounded system.

All ADV-X models 881, 882, and 883 are available in single phae and 3 -phase voltages. Single phase voltages are available in 115 VAC and 240 VAC .3 phase voltages are available in 240VAC, 480VAC, and 575VAC. ADV-X model 884 and 885 are available in 3 phase voltages only. YOUR LOCAL CODES MAY REQUIRE THAT THE INCOMING POWER TO YOUR DOOR HAVE A LOCK-OUT / TAG-OUT EQUIPPED FUSED DISCONNECT SWITCH (TO BE FURNISHED BY OTHERS) WITHIN EYESIGHT OF THE DOOR'S CONTROL PANEL. Incoming power wiring must meet all NEC and local building codes, plus be properly sized for the control panel's amperage rating on the nameplate. To reduce the risk of electric shock, the chassis of the control panel must be properly grounded.

## A WARNING

To avoid serious injury or death:
-It is recommended that line voltage wiring be performed by a qualified electrician.
-Be sure that electrical power has been disconnected from the input wires being connected to the operator prior to handling these wires. An appropriate lock-out/tagout procedure is recommended.
-Line voltage must meet all local building codes.
-Make sure operator voltage, phase, and frequency ratings are identical to the job site line voltage ratings.
-Input power wiring must be properly sized for the operators amperage rating.

## A WARNING

To avoid serious injury or death DO NOT calibrate motor or operate door unless doorway is in sight and free of obstructions. Keep clear of opening while door is moving.

## SECTION 5 - HIGH VOLTAGE WIRING (continued.....)

## DANGER

Before beginning this phase of installation, ensure POWER SUPPLY is disconnected to avoid serious injury or death!

## MOTOR \& POWER WIRING (HIGH VOLTAGE) (These tasks are also diagrammed in Fig 25, 26, and 27 on pages 21-23.)

A. Route Motor Power Cable (provided, factory wired to motor) through water-tight fitting in the SECOND hole from left side of Control Panel bottom.

1. Connect the lighter gauge, twisted pair wires to the blue colored Motor Brake terminals next to the disconnect switch. Either wire can connect to either terminal It is labeled "B1" and "B2".
2. Connect the green and yellow ground wire, the braided cable shield and the non-insulated ground wire together to the Green and Yellow terminal.
3. Connect the thicker motor wires to Terminals T1,T2 and T3 on the green screw connectors on the bottom left of the control unit. The order doesn't matter since the motor rotation can be changed using the internal programming during Set-up in Section 6.

## A licensed electrician must perform the following step.

B. Route Main Power Cable (not provided) through a
water-tight fitting (not provided) in the FIRST hole from the
left side of the Control Panel bottom.

- Connect 3-phase power lines to the disconnect. Connect
the ground wire to the Ground Terminal to the left of the disconnect.



## SECTION 5 - HIGH VOLIAGE WIRING (continued.....)

Fig 26 Control Panel Contents (See also FIG 8-H)


SECTION 5 - HIGH VOLTAGEWIRING (continued.....)


Fig 27 Control Panel Wiring Diagram (480V)

## SECTION 6 - INITIAL STARTUP PROCEDURE

STEP 1 APPLY POWER (LINE VOLTAGE)
Turn the disconnect handle Clockwise to the ON position in order to apply power to the Control Panel. A blue splash screen will pop up displaying the default profile, and controller data (consists of serial number, output capacity, software version, etc). Verify the system motor rating, and power ratings correspond with each other.
NOTE* The system information can also be accessed in the SYSTEM STATUS > OVERVIEW menu. (see page 35-37)

## STEP 2 IIITIAL LIMIT SETUP

The first time the controller is powered on, you must first set the limits. The LED screen will flash with the error E17, and you must reset the limits. This will also occur whenever the position sensor is disconnected from the controller. The position sensor, photoeyes, sensing edge, and interlock switch must be connected before the limits can be set. If, for any reason, the limits cannot be set, please refer to troubleshooting section 8 .
A. To enter the Menu, press and hold the OPEN, STOP, CLOSE membrane buttons for 3 seconds. A count down timer on the top left corner of the LED screen will display the remaining time left to hold. Refer to Fig 7-A on page 26 for the complete menu structure.

B. Holding the Stop button for 1 second will go back up a level in the Menu. Continuing to hold the STOP button will continue to go back up the menu structure until the main screen.
C. Once in the main screen, a 25 second countdown timer will show on the upper left hand corner. This countdown timer displays how long until the OPEN/STOP/CLOSE buttons will no longer give access to the MENU. Once inside the menu, use the OPEN button to scroll up, STOP button to enter, and CLOSE to scroll down. Pressing OPEN/STOP/CLOSE immediately exits the counter.
Note: Instead of using the front panel buttons one can access the menu from the control unit using menu/enter, the $\boldsymbol{\Delta}$, and $\boldsymbol{\nabla}$ buttons.

1. Enter the Menus
2. Scroll down until you reach the LIMIT SETUP and hit enter.
3. Scroll down and enter into Quick Setup. A code request screen will appear. Enter the 3 digit pass code to gain access by scrolling up or down. Your pass code is located on a separate addendum.
NOTE: Do not display or freely give out the pass code.
4. Follow the prompts in order to set the open and close limits on the door. During this time, use the OPEN, CLOSE buttons to move the door. Again, the STOP button will be used as the ENTER function. If no error has occurred, it will then display QUICK SETUP DONE, otherwise if failed; QUICK SETUP ABORTED and it must be redone. Refer to Trouble shooting section 8 if required.
NOTE: Even if the door moves in the opposite direction, proceed with the steps in order. You will have the option to reverse polarity later.
NOTE: When setting the position, the position sensor count will be displayed. Verify the encoder count increases when the door is moving in the up direction, and does not roll over to the negative position.

## SECTION 6 - INITIAL STARTUP PROCEDURE (continued.....)

## A WARNING

All Entrapment Protection Devices are OFF in Emergency Jog and the Limits are NOT SET. Devices OFF while in Emergency Jog include: Edge Contact, Photoeye, Wall push buttons, Radio Control, Limit Sensors, Loop Detector, or any motion sensor used as either an actuator or an Entrapment Protection Device. Only the Interlock remains active.
Emergency Jog is the manual control for momentary operation of door via ARROW buttons on the membrane keypad or on the control unit. USE CAUTION WHILE SETTING UP THE DOOR IN THIS MODE, AND KEEP OPENINGS CLEAR OF PERSONS AND PROPERTY TO AVOID SERIOUS INJURY OR DEATH! Do NOT use Emergency Jog for general door operation.

STEP 3 PAIR THE WIRELESS SENSING EDGE HOST (SEYWAVE HOST)
The wireless sensing edge host must be paired with the controller.
A. Enter the Menus
B. Scroll down until you reach the SYSTEM CONFIG and hit enter.
C. Scroll down and enter into OPTIONS. A code request screen will appear. Enter the 3 digit passcode to gain access by scrolling up or down. Your pass code is located on a separate addendum.
D. Select SeyWave Host
E. Select enable and make sure the black box is positioned on enable. If not, select enable and press menu/enter once. The black box will move to enable. Press and hold the menu/enter for a second to back out 1 screen.
F. Select clear all and press up to confirm.
G. Select pair and press the sensing edge. The controller will make a beeping noise when the pairing is complete.
H. Press and hold the menu/enter to go back to the home screen.

## STEP 4 VERIFICATION

Test each sensor to make sure the controller recognizes the fault.
A. Photoeyes -Obstruct the beam with a sold object. Photoeye should reverse door direction.
B. Sensing Edge -Place a solid object, taller than 12", on the floor and close the door. Sensing edge should reverse door direction on contact with object.
C. Interlock Switch -This is a constant activation sensor, release the hand chain from the switch, the door should stop and a fault display
NOTE: all faults and sensor activations are logged into the Fault Log. Access this through the menu SYSTEM STATUS > FAULT LOG in the Controller Menu. To clear faults hold the STOP button for 1 second once the fault has been fixed.

## STEP 5 SET SENSING EDGE SENSITIVITY

If you are in a high wind area you may need to adjust the sensitivity of the safety edge so that it does not trigger due to a high wind event.
A. Enter the Menus
B. Scroll down until you reach the SYSTEM CONFIG and hit enter.
C. Scroll down and enter Options. Then select Seawave host pairing. Then select impact adjust and preset.
D. Now make your sensitivity selection low, medium, or high.

## SECTION 7 - MENUS

## PART 1 EXPRESS MENU

The Express Menu is accessed by scrolling up, when at the idle screen or after exiting the menus. The express menu contains display options, timers, settings reset, and the emergency JOG. The timer functions in the Express Menu are shortcuts to timers in the system configuration menu without the need of a pass code.


## SECTION 7 - MENUS (continued.....)

PART 2 SYSTEM STATUS MENU
The System Status menu is read-only and provides parameter status displays for use in setup and troubleshooting. The options of the System Status menu are shown and described below. The controller is fully operational within this menu, allowing real-time
parameter updates. To use the System Status menu:
A. Enter the System Status menu
B. Scroll down and highlight a menu option.
C. Enter to view the highlighted option.
D. Press and hold STOP or ENTER when finished to return to the System Status menu.
E. Repeat to view other parameters if desired.

| Overview |  |
| :--- | ---: |
| Photocell 1: | OK |
| Safety Edge 1: OK |  |
| Position: | 123 |

Overview displays status and current position of Photocell and Safety Edge (reversing edge)

1. To view status and current position of photocell
2. Safety Edge 2, scroll up.
```
\begin{tabular}{|l|}
\hline \multicolumn{2}{|c|}{ Position } \\
\hline Position: \(\quad 123\) \\
Battery OK \\
\hline
\end{tabular}
```

Position shows the internal door position count. The battery level and status
are shown

```
Inputs
```



``` X4:
```



```
Outputs Outputs provides an overview of the controller outputs. Box is marked if the corresponding
Relay: \amoln controller output is active.
NPN: 口I
controller output is active.
```

```
    Log}1\mathrm{ of 10
Error: E10
On Cycle: 045
```

Inputs provides an overview of the controller inputs. Box is marked if the corresponding
controller input is active.

Fault log displays error code and door operation cycle for the last 10 faults. Scroll up or down to navigate through the fault log.

Cycle counter shows the number of operating cycles the door has completed (open/close = 1 cycle). Note: This is already shown by default at the top left corner in the main screen.

| DCLink |
| :---: | :---: |
| 330 V |
| $300-370 \mathrm{VDC}$ |$\quad$ DC Link shows the internal DC Link voltage along with the acceptable range.


| Int Levels |  |
| :--- | ---: |
| Int $12 \mathrm{~V}:$ | 11.5 V |
| Int 24V: | 22.0 V |

INT Levels shows the control's actual internal supply voltages.

To avoid potential equipment damage do not change the controllers profile unless advised to do so by your plant service technician. There are multiple 885 profiles. You will need the correct one based on your particular door and motor configuration.

## PART 3 PROFILE SELECTIONMENU

The profile selection is done at the factory by default. Profiles can be selected based on the door the
controller is operating. The profile is protected by a passcode, and can only be changed by Overhead service representative. All settings are lost and reverted back to defaults when the profile is changed. Profiles can be accessed through the main menu under Profile Selection.

## PART 4 LIMIT SETUP MENU

Individual limits can be updated manually, however; the best option is to use the quick setup process as discussed earlier. The door will not be operational when setting limits. Limit settings are as described below.

## A WARNING

All Entrapment Protection Devices are OFF when setting limits. Devices OFF while setting Limits include: Edge Contact, Photoeye, Wall push buttons, Radio Control, Limit Sensors, Loop Detector, or any motion sensor used as either an actuator or an Entrapment Protection Device. Only the Interlock remains active. USE CAUTION! KEEP OPENINGS CLEAR OF PERSONS AND PROPERTY TO AVOID SERIOUS INJURY OR DEATH! Do NOT use for general door operation when setting limits.

To configure the Limit Settings manually after using Quick Setup, select each individual position listed below from the Limit Setup menu, then move the door to the desired position. Store the position by pressing STOP or ENTER when finished. The display shows Stored and returns to the previous menu.

- Closed: Door fully closed.
- Pre Closed: Position where door changes to pre-closing speed during close.
- Pre Open: Position where door changes to pre-open speed during open.
- Open: Door fully closed.
- Open Part 1: Partially open position 1. Door opens to this position when a part 1 open input is active. (default: $75 \%$ of door open limit)
- Open Part 2: Partially open position 2. Door opens to this position when a part 2 open input is active. (default: $50 \%$ of door open limit)
- Rev. Edge OFF: Sets door position where safety edge check is turned off: the limit where the reversing safety edge should be ignored.
- Photocell Off: Sets door position where photocell should be ignored.



## SECTION 7 - MIENUS (continued.....)

PART 5 SYSTEM CONFIGURATION MENU
This menu contains all editable parameters on the door system. A passcode is required in order to change the settings. The door will not operate when inside the menu.
A. Timers

1. Contains all the same timers in the Express Menu.
2. Setting the timer to 0 disables the timer.
B. Outputs - Configurable relay activation based on custom door status/events. Table on page 40 lists all available status/events.
C. Inputs - Inputs with configurable actuator functions. Table on pages 31-32 list all functions available with each input.
D. Position sensor -Do not update/menu is not used
E. Reference-Do not update/menu is not used.
F. Safety Edges -Do not update / Menu not used.
G. Photoeyes -Do not update/menu is not used
H. Motor Configuration - Do not update / Engineering use only.
I. Frequencies - Do not update / Tech Services use only.
J. Ramps - Do not update / Tech Services use only.
K. DG-XNET -Do not update / Menu not used.
L. Options -Menu to access the pairing of the wireless sensing edge host.
M. System -Do not update / Engineering use only.

## CONFIGURATION INPUT/OUTPUTS

A. Inputs. There are 3 parameters that can be set. Refer to FIG 7-C (close up view of Input relays)

1. Function -A list of functions can be selected to determine how the input should operate the door.
2. Name -a name can be applied to the specific function
3. Logic -The logic for activation of the door can be chosen. Either Normally Open (0VDC ->24VDC) or Normally Closed (24VDC ->0VDC).
B. Outputs. Refer to FIG 7-D (close up view of Output relays)

1 Function -list of functions can be selected to activate the output relay
2. The output is dependent on the input wired into the relay pins $2,5,7,9$.
3. Output relays $1 \& 2$ consist of two relay outputs, a NO and NC. Output Relays $3 \& 4$ contain only NO relay activation.

SECTION 7 - MENUS (continued.....)
PART 5 SYSTEM CONFIGURATION MENU (continued.....)

| INPUT SIGNAL | ACTIVATION DESCRIPTION |
| :---: | :---: |
| Manual | Momentary activation opens door unless the door is already at an open position. In this case, the door will close. <br> 1) If the Manual timer is set to a value greater than zero, the controller delays closing of the door until the timer expires. |
| Open | Opens the door to fully open position when activated. |
| Auto 1 | Momentary activation opens door to the fully open position limit. Upon deactivation the controller delays the door for the duration of the Auto timer. If reactivated during this time delay, the timer will be reset and will begin to decrement when the input is again deactivated. Upon expiration of the timer, the controller closes the door to fully closed position. If timer is not used, the door will stay in the open position when activated. |
| Stop | Momentary activation stops the motion of the door. This input uses the Stop Deceleration Ramp set under the System Config menu. This input is also used to clear certain error conditions. |
| Close | Closes the door to fully open position when activated |
| Emergency Stop | Activation immediately halts the door in motion. This input uses the Emergency Deceleration Ramp set under the System Config menu. |
| Safety Edge | Activation during a closing cycle stops the door and then reverses the door motion back to the fully open position limit. An "E10 Safety Edge Activated" error occurs. |
| Photoeye | Activation during a closing cycle stops the door and then reverses the door motion back to the fully open position limit. |
| Lock Open | Activation causes the controller to hold the door at the fully open position limit. The input must be continuously activated to maintain the locked open state. Deactivating this input unlocks the door and allows normal operation. |
| Lock Close | Activation causes the controller to hold the door at the fully closed position limit. The input must be continuously activated to maintain the locked open state. Deactivating this input unlocks the door and allows normal operation. |
| Open Jog | Activation of this input moves the door in the direction of the fully open limit at Jog speed. Deactivating this input stops the door in motion. Activation during closing does not open or stop the door. |
| Close Jog | Activation of this input moves the door in the direction of the fully closed limit at Jog speed. Deactivating this input stops the door in motion. Activation during opening does not close or stop the door. |
| Breakaway | Activation halts door motion. |
| Open Position 1 | Activation opens the door to the partial open 1 position limit. If activated during closing, door will reverse to 1 position limit. |
| Open Position 2 | Activation opens the door to the partial open 2 position limit. If activated during closing, door will reverse to 2 position limit. |
| Open Part 1 Auto | Activation opens the door to partial open 1 position limit. The controller then delays the door for the duration of the Auto Timer. Upon expiration of the timer, the door closes fully. |
| Open Part 2 Auto | Activation opens the door to partial open 2 position limit. The controller then delays the door for the duration of the Auto Timer. Upon expiration of the timer, the door closes fully. |
| Flip Flop | Activation reverses the door operation. If door is closed, activation opens the door and vise versa. When door is closing and activated, the door reverses and begins opening and vise versa. |
| Man Part 1 | Activation opens the door to the partial open 1 position limit, if not already at this position. If the door is already at this position, the door closes. |
| Man Part 2 | Activation opens the door to the partial open 2 position limit, if not already at this position. If the door is already at this position, the door closes. |



Fig 7-C

SECTION 7 - MENUS (continued.....)
PART 5 SYSTEM CONFIGURATION MENU (continued....)

| INPUT SIGNAL |  |
| :--- | :--- |
| Door Moving | Output is active when the door is in motion. |
| Door Not Moving | Output is active when the door is not in motion. |
| Door Open | Output is active when the door is at the fully open position. |
| Door Closed | Output is active when the door is at the fully closed position. |
| Door Not Closed | Output is active when the door is above the fully closed position. |
| Door Open Partial | Output is active when the door is at open part 1 position. |
| Door Opening | Output is active when the door is moving in the open direction. |
| Door Closing | Output is active when the door is moving in the close direction. |
| Delay to Close | Output is active when the Delay To Close timer is greater than zero and the door is commanded to close. The output remains active for the duration of the Delay To <br> Close timer. |
| Delay to Open | Output is active when the Delay To Open timer is greater than zero and the door is commanded to open. The Open button must remain active until the Delay To <br> Open timer has expired, the output will be active during this time. Upon expiration of the timer, the door opens and the output is deactivated. |
| Auto Close Active | Output is active for the duration of the Auto or Man timer during an auto close sequence. |
| System Error | Output is active when DGIl is in any error condition. |
| Pre Warning Active | Output is active for the duration of the Auto Timer and during any close sequence. |
| Open Alarm Active | Output is active when Open Alarm Timer is greater then zero. |



Fig 7-D

How to use the keypad to retrieve operation events, fault/shutdown messages, and system status (Also see Section 8-Troubleshooting)
A. With the unit idle enter the System Status menu.
B. Scroll through the list of choices until you reach the Fault Log menu and enter.
C. Scroll through the list until you reach the information you're looking for.
D. When finished exit the menus and return to the main screen.

NOTE: The items in the Fault Log are listed in reverse chronological order with number 1 being the most recent and the highest number being the oldest.

- If NO keys are pressed for 120 seconds, display will exit back to the main menu.
- Motion can occur and panel responds normally to inputs while in the System Status Menus.


## FAULT LOG

```
    Log}1\mathrm{ of }1
Error: E10
```

On Cycle: 045

PART 7 SETUP CHECK LIST

## A WARNING

Check ALL items below to ensure that the Control Panel is installed and operating properly and entrapment protection is working properly.
A door system that is not properly setup can cause death or serious injury.

## CHECK

- The door operates using all installed control devices.
- The door runs to its full open and full closed positions.
- The Entrapment Protection Device(s) will reverse a closing door when actuated.
- The proper Actuator selections are made to activate timers.
- The Hand Chain interlock switch prevents motor/door movement when the hand chain is pulled.

If the panel is in a location where public access is possible, install a means to limit access to the inside of the panel.

## SECTION 8 -TROUBLESHOOTING THE CONTROLLER



| TROUBLE | POTENTIAL CAUSE | NOTES / CORRECTIVE ACTION |
| :---: | :---: | :---: |
| Door will not move | Door may be in Shut Down mode. Fix issue. | Press stop key to clear fault. |
|  | No power | Check motor wiring, power line, system rating. |
| Timed Close not functioning | Timer is set to 0 . | Verify or update specific timer in express menu.. |
|  | Timer condidtion not met. | Verify door is at open close limits, or condition is met. |
| Auto 1/ Manual 1 Function not working | Wiring or connection loose, signal not reaching controller. | Verify connections. |
|  | Auto 1/Man 1 not selected as function. | Verify chosen input function. |
| On key release, door stops or reverses | One of the sensor inputs activated. | Verify sensor inputs. |
| Timed Close quits after a few reverses | After a factory set number of failed attempts, usually three, the door will stop attempting to Time Close after a reversal. This is normal door function. | Door will reverse a Timed Closed door without counting the first reversal as a failed attempt. NOTE: If Entrapment Prevention Inputs cause reversals in the meantime, the reversals will continue to count as failed attempts and stop the close timer after three tries. |
| Wall push button not responding. | Wiring and firmware setting incorrect. | Common should be set to 24 V <br> Stop is set to NC in firmware (System config > Inputs) <br> Open is set to NO. <br> Close is set to NO. <br> Refer to Fig 8-B page 36 |
| General service Due: XXXXX | Routine service interval has elapsed. | Contact distributor for required maintenance. |
| Major service Req'd XXXXX | Required maintenance interval has elapsed. | Contact distributor for required maintenance. |
| Door stops for no reason, or acts differently than before - No errors displayed, only shows IDLE at status | A brownout or short has affected the controller | Use the disconnect switch to turn off the power, wait until the unit shuts off, then turn it back on (hard reset). <br> -Contact customer service if it is still an issue. |
|  | Possible overheat | Check fault log |
| One of the options to the Junction Box does not operate as expected | Connection to the Junction Box is incorrect | Ensure the Junction Box connections are correct (Via Manual) <br> 1. Radio Remote Receiver is wired to Manual1 input <br> -A 10 kohm load is also needed to be wired from the Manual1 input to a 24VDC connection (part of the kit when delivered). <br> 2. Loop Detector or Motion Detector is wired to Option 1 (or to an Auto 1 input) NOTE* Both can be wired, but one needs to be wired directly to the Control Unit (regular wire can be used) |
| Quick setup aborted | Fault occured when setting limits | 1. Fix faults in system. <br> 2. Make sure Position Sensor does not roll over from $+32,000$ to $-32,000$ when setting limits. <br> 3. Make sure Position count increases when setting door to open limit (door direction incorrect). <br> 4. Restart Quick Setup. |
| Door limits have shifted | Position Sensor fault/failure | 1. Verify Position Sensor connections. <br> 2. Verify magnet in position sensor has not moved and has not rubbed against the encoder. <br> 3. Reset limits. |



| MESSAGE DISPLAYED | CAUSE | NOTES / CORRECTIVE ACTION |
| :---: | :---: | :---: |
| ------------ | Displayed if no message code is present in the Event or Error Log. | Contact service representative. |
| STATUS |  |  |
| Idle | Door at rest, not at open, close, mid limits. | Displayed when door is motionless in Idle and not at open, close, open P1 limits. Door stopped using the STOP key. |
| STATUS |  |  |
| Count down | Door at rest and counting down to timed close or open. | Time remaining in seconds is displayed. |
| STATUS -OPENING |  |  |
| Opening | Door opening. | Displayed while door is opening from activation. |
| STATUS - CLOSING |  |  |
| Closing | Door closing. | Displayed while door is closing from activation. |
| STATUS -STOP |  |  |
| Stop | Door stopping. | Displayed while door is stopping from activation. |
| STATUS |  |  |
| Locked | Incorrect pass code input. | Displayed when the wrong pass code is entered |
| Closed | Position at close limit. |  |
| Open | Position at open limit. |  |
| Open P1 | Position at 75\% of open limit. |  |
| Open P2 | Position at mid limit. |  |


| CODE | DESCRIPTION | PROBLEM | POSSIBLE SOLUTION |
| :--- | :--- | :--- | :--- |
| INV_ERROR_UU | DC Link low <br> (Top Priority) | The incoming mains voltage is too low | View System Status - DC Link to check that the voltage is within the range shown. |
| INV_ERROR_OU | DC Link high <br> (Medium Priority) | Either the incoming mains voltage is too high <br> or the deceleration rate is to short | View System Status - DC Link to check that the voltage is within the range shown. <br> Decrease the deceleration ramps. |
| INV_ERROR_OC1 | Overcurrent 210\% <br> (Low Priority) | The motor current exceeds the inverter rating <br> by 210\% | View the Motor Current display to check the current delivered to the motor. Check <br> the motor nameplate data to confirm that the correct controller model is being <br> used. Check for mechanical obstruction or damage. |
| INV_ERROR_OC2 | Overcurrent 150\%/30 sec <br> (Low Priority) | The motor current exceeds the inverter rating <br> by $150 \%$ for more than 30 seconds | View the Motor Current display to see the current delivered to the motor. Check <br> the motor nameplate data to confirm that the correct controller is being used. <br> Check for mechanical obstruction or damage. |
| INV_ERROR_OC3 | Overcurrent during acceleration | Overcurrent while accelerating | View the Motor Current display to see the current delivered to the motor. Decrease <br> the acceleration ramps |
| INV_ERROR_OC4 | Overcurrent DC/Brake <br> (Medium Priority) | Overcurrent while DC braking | View the Motor Current display to see the current delivered to the motor. Decrease <br> the DC Brake level. |
| INV_ERROR_OC5 | Peak overcurrent <br> (High Priority) | Check for: <br> a short in the motor cable <br> stalled motor <br> mechanically or electrically damaged motor. |  |
| If equipped with a parking brake, ensure that it is being released. Decrease the |  |  |  |
| Boost parameters. |  |  |  |$\quad$| Severe overload |
| :--- |
| INV_ERROR_OH |
| Controller overheat |
| (High Priority) |


| CODE | DESCRIPTION | PROBLEM | POSSIBLE SOLUTION |
| :---: | :---: | :---: | :---: |
| E01 | Slip error (Low Priority) | Mechanical overload (Slip Monitoring) or missing signal from encoder. | Check door for obstruction. <br> Ensure the pulse output from the encoder is connected to terminal P2 on the controller. Verify that the encoder pulse output is set correctly. |
| E02 | Direction Error - occurs during setup only (Low Priority) | The direction of the motor is incorrect. The encoder count must increment positively while the door is moving in the open direction. | Use the Motor Direction parameter to set the correct direction for the motor and encoder. |
| E03 | No Signal From Pulse Generator - occurs during setup only. (Low Priority) | No pulse input detected from the encoder. | Check door for obstruction. <br> Ensure the pulse output from the encoder is connected to terminal P2 on the Controller. <br> Verify that the encoder pulse output is set correctly. |
| E04 | Speed Error | Door moves faster/slower then Expected | Check door for obstruction. |
| E05 | N/A |  |  |
| E06 | N/A |  |  |
| E07 | Run Timer Exceeded (Low Priority) | The Run Timer has expired. | Check the Run Timer parameter to ensure a correct value. |
| E08 | Safety Edge Test Fail (Medium Priority) | The Reversing Edge test has failed | Check the connections from the reversing edge to the controller. If using the Seywave wireless system, check operation of connected host and remote door sensor. |
| E09 | Safety Edge Connection (Medium Priority) | The Reversing Edge connection cannot be verified. | Check the connections from the reversing edge to the controller. If using the Seywave wireless system, check operation of connected host and remote door sensor. Verify Safety edge is not activated. |
| E10 | Safety Edge 1 Activated (Low Priority) | The Reversing Edge has been activated | Check for obstruction in door's path. |
| E11 | Safety Edge 2 Activated (Low Priority) | The Reversing Edge has been activated | Check for obstruction in door's path. |
| E12 | Lifting Force Exceeded (Low Priority) | The torque limit has been exceeded | If the torque limiting feature is being used, adjust the Torque Limit parameter to suit the application. |
| E13 | No Encoder movement | Encoder did not move when expected | Check for obstruction. Check connection from Position Sensor to Motor. |
| E14 | Absolute Encoder Comm Loss (Top Priority) | Communication with the absolute encoder has been lost. | Check the connections between the encoder and the controller. |
| E15 | Installation Fault (Low Priority) | An error occurred during Quick Setup | Re-perform Quick Setup |
| E16 | Encoder fault | Encoder communication is not correct | Check Position Sensor. Verify connections. |

SECTION 8 -TROUBLESHOOTING THE CONTROLLER (contd.....)
PART 4 CONTROL PANEL ERROR MESSAGES - DOOR CONTROL ERROR CODES (continued.....)

| CODE | DESCRIPTION | PROBLEM | POSSIBLE SOLUTION |
| :--- | :--- | :--- | :--- |
| E17 | Reset Limits <br> (HIGH PRIORITY) | The position limits cannot be verified | Perform a Quick Setup |
| E18 | Wireless Airlock Failed to <br> Authorize Opening <br> (Low Priority) | The controller failed to receive an Airlock request <br> acknowledgement. | Check opposite controller to ensure that it is operational. Check that both controllers <br> have been wirelessly connected together and that each controller has Wireless and <br> Airlock enabled. Disconnect controllers and run a discovery to reconnect controllers. |
| E19 | Wireless No Response | There was no response from the onboard wireless | Ensure that the Wireless is Enabled then power cycle the controller. |
| E20 | Backroll error | Door movement when at idle state | Verify there are no obstructions, verify motor gear box is functional. |
| E21 | Option - Seywave OCS <br> Remote Timeout | A paired Seywave wireless O/C/S remote has timed out. |  |

PART 5 CONTROL PANEL ERROR MESSAGES - ERROR CODE PRIORITY LEVELS

| Priority Level | Reset Condition |  |
| :--- | :--- | :--- |
| Low | Activation input | Can also be reset by higher priority reset conditions |
| Medium | Stop, E-Stop or Menu/Enter button pressed | Can also be reset by higher priority reset conditions |
| High | Menu/Enter button pressed and held for 2 seconds. | Screen Flashes |
| Priority Reset Limits | Successful Quick Setup | Auto-clears when limits are set |
| Priority Encoder Connection | Communication restored between encoder and controller | Auto-clears when fault no longer exists |
| Priority INV_ERROR_UU | Incoming main voltage is within range | Auto-clears when fault no longer exists |
| Priority INV_ERROR_12VInternal 12V | Internal 12V DC level is within range | Auto-clears when fault no longer exists |
| Priority INV_ERROR_24V | Internal 24V DC level is within range | Auto-clears when fault no longer exists |

## A WARNING

Failure to perform specified service and maintenance may result in an unsafe condition, will void limited warranty, and may result in premature failure of the unit. Service and Maintenance are necessary to ensure safe operation of the ADV-X door.

| INSTALLATION DATE: <br> SERVICE ITEM |  |  |  | INSTALLER INITIAL: <br> SERVICE INTERVAL (frequency) |
| :--- | :---: | :---: | :---: | :---: |



Fig 9-B

## General Maintenance Interval Message

- Upon reaching 150,000 door cycles (300,000 \& 450,000, etc.), the panel will display general maintenance needed.
- Contact your distributor to have required maintenance performed.
- Once service is completed, clear the service message by going into System Configuration ->System -> Clear Service.


## Sensing Edge \& Photoeye systems

- Test sensing edge activation daily.
- Place a solid object, higher than 12", on floor and close door. Sensing edge should reverse door direction on contact with object.
- Test Photoeye activation daily.
- Obstruct the Photoeye beam with a solid object. Photoeye should reverse door direction.


## General Inspection

- Visually inspect wiring conduit and cables.
- Inspect fixtures such as: Bearings, conduit boxes, hood, gear box (for oil leakage), motor.
- Inspect safety labels, placement and condition.
- Lubricate guides with paste wax or silicone spray.


## Position Sensor Chain Tension and Alignment

- Check sprocket alignment.
- Check chain tension, max sag is 1/2", Fig. 9-B.
- Lubricate chain.


## Manual Operation of Door

- Inspect door alignment and level.
- Inspect curtain and endlocks for damage.
- Inspect guides, sensing edge and hood for damage.


## Mounting Bolt Tightness

- Check fasteners anchoring headplates and door guides to wall.


## Check Limit Position

- Verify the door stops at correct open position.
- Verify that door closes fully without excessive "stacking" of curtain in guides.
- Verify approach speeds provide for smooth starts and stops.
Keep records of all service and maintenance.


## mom

## ADV-X High Speed Fabric and Rubber Doors

## Limited Warranty


 workmanship under normal use for the following periods, measured from the date of installation::

- Seller warrants all mechanical door system components and the control panel hardware for a period of 60 MONTHS
Seller's obligation under this warranty is specifically limited to repairing or replacing, at its option, any part which is
determined by Seller to be defective during the applicable warranty period. Repair or replacement labor for any determined by Seller to be defective during the applicable warranty period. Repair or rep
This warranty is made to the original purchaser of the Product only, and is not transferable or assignable. This

 or deterioration caused by door fabric and/or rubber curtain rubbing together as the door rolls up upon itself,
puncture, or caused by exposure to salt water, chemical fumes or other corrosive or aggressive environments, sand, dirt or grease.
THIS WARRANTY IS EXCLUSIVE AND IN LIEU OF ANY OTHER WARRANTIES, EITHER EXPRESS OR IMPLIED
INCLUDING BUT NOT LIMITED TO ANY IMPLIED WARRANTY OF MERCHANTABILITY OR FITNESS FOR A
PARTICULAR PURPOSE.
IN NO EVENT SHALL SELLER BE RESPONSIBLE FOR, OR LIABLE TO ANYONE FOR, SPECIAL, INDIRECT,
COLLATERAL, PUNITIVE, INCIDENTAL OR CONSEQUENTIAL DAMAGES, even if Seller has been advised of the
 loss of use, cost of any substitute product, interruption of business, or other similar indirect financial loss.

 alteration of its condition. Proof of the purchase and/or installation date, and identification as the original purchase DOOR MODEL: ORIGINAL PURCHASER: INSTALLATION ADDRESS: SELLER:


## SELLER'S ADDRESS

 FACTORY ORDER \#: DATE OF INSTALLATION: SIGNATURE OF SELLER:
[^0]:    : CAUTION
    ADV-X Door Models must be supplied by a grounded Wye voltage supply, e.g. $208 \mathrm{Y} / 120,480 \mathrm{Y} / 277$. Ungrounded voltage supply sources must be avoided, e.g. 480 VAC, 240 VAC or 120 VAC Delta systems should NOT be used. Voltage unbalance is a common occurrence on Delta supply systems, which power both single phase and three phase loads, which can lead to unequal voltages on each phase leg. Voltage unbalance can cause deterioration of motor performance, such as loss of torque, overheating, decrease the winding insulation life, and can cause motor starter contacts, located in the control panel, to permanently "weld" closed. Voltage unbalance can be caused by inadequate conductor sizing, Delta transformer sizing, excessive single-phase loads, poor grounding, or intermittent high resistance faults (Faults which do NOT generate high - enough fault currents to trip an Over Current Protection device, but will cause the distributed capacitance in an ungrounded three phase system to shift. This shift may cause destructive over-voltages to occur).
    Overhead Door Corporation's warranty WILL NOT cover damage caused by failure of the motor, control panel or other electrical components due to the use of an inadequately grounded system.

